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that $y_i[n] = x[n] * h[n] = \sum_k h[k]x[n-k]$ (S2.1-1) The signals $x[n]$ and $h[n]$ are as shown in Figure S2.1. From this figure, we can easily see that the above convolution sum reduces to $y_i[n] = h[-1]x[n+1] + h[1]x[n-1]$

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Discrete-time processing of continuous-time signals : 19: Discrete-time sampling : 20: The Laplace transform : 21: Continuous-time second-order systems : 22: The z-transform : 23: Mapping continuous-time filters to discrete-time filters : 24: Butterworth filters : 25: Feedback : 26

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These lecture notes were prepared using mainly our textbook titled "Signals and Systems" by Alan V. Oppenheim, Alan S. Willsky and S. Hamid Nawab, but also from handwritten notes of Fatih Kamisli and A. Ozgur Yilmaz. Most figures and tables in the notes are also taken from the textbook. This is the first version of the notes.

Lecture Notes EE301 Signals and Systems I

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Alan Victor Oppenheim (born 1937 in New York City) is a Professor of Engineering at MIT's Department of Electrical Engineering and Computer Science. He is also a principal investigator in MIT's Research Laboratory of Electronics (RLE), at the Digital Signal Processing Group. His research interests are in the general area of signal processing and its applications.

Alan V. Oppenheim - Wikipedia

Haykin and Van Veen have designed Signals and Systems to be appropriate for both one- and two-semester sophomore-junior versions of the Signals and Systems course. The book's integrated, balanced treatment of continuous- and discrete-time forms of signals and systems is both a reflection of the topics' real roles in engineering practice and a clear, practical way of introducing the large range ...

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